Calculs topologiques sur les ensembles semi-algébriques Résultats récents et problèmes ouverts

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Main reference

Algorithms in Real Algebraic Geometry

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1 Introduction

- (1) count the number of real roots of a univariate polynomial, Sturm 1836
- (2)(ETR) decide whether a semi-algebraic set has a real solution Tarski 1939 (undecidable on integers Matiyasevich 1973)
- (3) decide whether a semi-algebraic set is connected cylindrical decomposition techniques: Lojasiewicz, Collins (1960-70)
- (4) stratification: decompose a semi-algebraic set in smooth manifolds of various dimensions by Collins cylindrical algebraic decomposition
- (5) compute the topological invariants (Betti numbers) of semi algebraic sets by CAD

complexity results

• two main methods for topology: cylindrical decomposition and critical point method.

- (2) (ETR) and (3) polynomial in s, d and τ , doubly exponential in k by CAD, singly exponential in k by critical points method (see Basu/Pollack/Roy)
- (4) and (5) polynomial is, d, and τ , doubly exponential k by CAD, singly exponential? partial results for Betti one (this talk Basu/Pollack/Roy 2004) for the first Betti numbers (Basu 2004)

complexity results (continued, special case of quadratic polynomials)

- ullet based on previous work of Barvinok: number of connected components polynomial in k
- (2') (ETR) in the quadratic case: polynomial in k (Grigor'ev Pasechnik)
- (3') polynomial in k? open
- (5') top Betti numbers: polynomial in k (Basu 2004) efficiency
- Fabrice Rouillier (using Jean-Charles Faugère Grobner basis computations)
- Mohab Safey, Philippe Trebuchet
- applications....

2 Cylindrical decomposition

2.1 Subresultants

$$P = a_p X^p + a_{p-1} X^{p-1} + a_{p-2} X^{p-2} + \dots + a_0,$$

$$Q = b_q X^q + b_{q-1} X^{q-1} + \dots + b_0$$

$$\mathrm{SH}_{j}(P,Q) = \begin{pmatrix} a_{p} & \cdots & \cdots & \cdots & a_{0} \\ & \ddots & \ddots & \ddots & \ddots & \ddots \\ & & a_{p} & \cdots & \cdots & \cdots & a_{0} \\ & & b_{q} & \cdots & \cdots & b_{0} \\ & & b_{q} & \cdots & \cdots & b_{0} \\ & & \ddots & \ddots & \ddots & \ddots \\ & & b_{q} & \cdots & \cdots & b_{0} \end{pmatrix} \quad p-j$$

$$\stackrel{i. th. (signed)}{\underbrace{b_{q} & \cdots & \cdots & b_{0}}_{p+q-j}}$$

• j-th (signed) subresultant coefficient $\operatorname{sr}_{j}(P,Q)$: determinant of the square matrix obtained by taking the p+q-2j first columns of $\operatorname{SR}_{j}(P,Q)$

important for cylindrical decomposition

Proposition 2.1 $\deg(\gcd(P,Q)) = \ell$ if and only if

$$sr_0(P,Q) = ... = sr_{\ell-1}(P,Q) = 0, sr_{\ell}(P,Q) \neq 0$$

2.2 Cylindrical decomposition: doubly exponential complexity

- decomposition of a semi-algebraic set: partition in a finite number of semi-algebraic sets
- cylindrical algebraic decomposition of \mathbb{R}^k : sequence $\mathcal{S}_1, \ldots, \mathcal{S}_k$, where \mathcal{S}_i decomposes \mathbb{R}^i in cells, such that
 - a) $S \in \mathcal{S}_1$ is either a point or an open interval
 - b) for every $S \in \mathcal{S}_j$, j < k there exist semi algebraic functions $\xi_{S,j}$

$$\xi_{S,1} < \ldots < \xi_{S,\ell_S} : S \longrightarrow \mathbb{R}$$
,

such that the cylinder $S \times \mathbb{R} \subset \mathbb{R}^{i+1}$ is the disjoint union of cells of S_{i+1}

- * either a graph $\Gamma_{S,j}$, of one of the $\xi_{S,j}$, pour $j=1,\ldots,\ell_S$
- * or a band $B_{S,j}$ of the cylinder between the graphs of two functions $\xi_{S,j}$ and $\xi_{S,j+1}$
- subset S of \mathbb{R}^k \mathcal{P} -invariant: every polynimial $P \in \mathcal{P}$ has a constant sign (>0, <0, or =0) on S.
- cylindrical algebraic decomposition of \mathbb{R}^k adapted to \mathcal{P} :cylindrical algebraic decomposition such that each $S \in \mathcal{S}_k$ is \mathcal{P} -invariant

Théorème 2.2 For every finite $\mathcal{P} \subset \mathbb{R}[X_1, \dots, X_k]$, there exists a cylindrical algebraic decomposition of \mathbb{R}^k adapted to \mathcal{P} .

- idea: fix the degre of the gcd so that roots dont mix up
- use subresultant coefficient
- induction on number of variables
- elimination phase: iterated projection
- lifting phase : one point by cell
- algorithm very simple, Collins (1973)
- produces a lot of information
- solves (ETR) using sample points in cells
- semi-algebraic set: finite union of connected pieces, semi-algebraically homeomorphic to open cubes

- eliminates quantifiers (saturating first by derivatives)
- a cell is described by the sign condition realized at one of its points
- gives a stratification (saturating first by derivatives and making a linear change of coordinates)
- the closure of a cell is obtained by relaxing the sign conditions defining the cell
- gives connected components
- gives a triangulation
- reduces semi-algebraic algebraic topology to combinatorial algebraic topology
- gives all the Betti numbers
- inconveniences: complexity doubly exponential in the number of variables: eliminating one variable squares the degree.

3 Critical points method :single exponential complexity

- based on Morse, Oleinick, Petrowski, Thom, Milnor
- complexity: Grigori'ev/Vorobjov, Canny, Renegar, Heintz/Roy/Solerno, Basu/Pollack/Roy
- nonsingular bounded compact hypersurface $V = \{M \in \mathbb{R}^n , H(M) = 0\}$, i.e. such that

$$\operatorname{Grad}_{M}(H) = \left[\frac{\partial H}{\partial X_{1}}(M), \dots, \frac{\partial H}{\partial X_{n}}(M)\right]$$

does not vanish on the zeros of H in \mathbb{C}^n .

- critical points of the projection on the X_1 axis meet all the connected components of V
- except special cases, $d(d-1)^{k-1}$ such critical points (Bezout),

$$H(M) = \frac{\partial H}{\partial X_2}(M) = \dots, \frac{\partial H}{\partial X_n}(M) = 0,$$

3.1 At least a point in every connected component of an algebraic set

- reduction to smooth and bounded, with a finite number of critical points in the X_1 direction: infinitesimals and limits
- algebraic Puiseux series: computations with coefficients in $\mathbb{Z}[\varepsilon]$, be careful to bound degrees in ε during computations
- a point in every connected component of an algebraic set: finite number (single exponential) of critical points, which can be projected on a line
- RUR rational univariate representation (F. Rouillier)
- univariate techniques (Sturm, subresultants)
- complexity single exponential (polynomial in the number of critical points which is singly exponential)

Some details en the bounded algebraic case.

Suppose that

- $Q(x) \ge 0$ for every $x \in \mathbb{R}^k$,
- $Z(Q, \mathbb{R}^k) \subset B(0, 1/c)$ for some $c \leq 1, c \in D$,
- $d_1 > d_2 \cdots > d_k$
- $\deg(Q) \leq d_1$, $\deg_{X_i}(Q) \leq d_i$ (maximal total degree of the monomials in Q containing the variable X_i), for $i = 2, \ldots, k$,
- \bar{d}_i be an even number $> d_i, i = 1, \dots, k$, and $\bar{d} = (\bar{d}_1, \dots, \bar{d}_k)$.
- ζ be a variable and $\mathbb{R}\langle\zeta\rangle$ be the field of algebraic Puiseux series in ζ with coefficients in \mathbb{R} .

$$G_k(\bar{d},c) = c^{\bar{d}_1}(X_1^{\bar{d}_1} + \dots + X_k^{\bar{d}_k} + X_2^2 + \dots + X_k^2) - (2k-1),$$

$$Def(Q,\bar{d},c,\zeta) = \zeta G_k(\bar{d},c) + (1-\zeta)Q.$$

Take \lim_{ζ} corresponds to take $\zeta = 0$ (with some precautions).

Proposition 3.1 The algebraic set $Z((Q, \bar{d}, c, \zeta), \mathbb{R}\langle \zeta \rangle^k)$ is a nonsingular algebraic hypersurface bounded over \mathbb{R} .

$$\lim_{\zeta} (\mathbf{Z}((Q, \bar{d}, c, \zeta), \mathbb{R}\langle \zeta \rangle^k)) = \mathbf{Z}(Q, \mathbb{R}^k).$$

Moreover $Z((Q, \bar{d}, c, \zeta), \mathbb{R}\langle\zeta\rangle^k) \subset B(0, 1/c)$ and X_1 has a finite number of critical points on $Z((Q, \bar{d}, c, \zeta), \mathbb{R}\langle\zeta\rangle^k)$.

 X_1 -pseudo-critical points are limits of X_1 -critical points on $Z((Q, \bar{d}, c, \zeta), \mathbb{R}\langle\zeta\rangle^k)$. They meet every connected component.

3.2 ETR: existential theory of the reals

• a point in every connected component of a semi-algebraic set: uses a new infinitesimal

Proposition 3.2 C connected component of a set defined by $P_1 = \cdots = P_{\ell} = 0, P_{\ell+1} > 0, \cdots, P_s > 0$. There exist indices i_1, \ldots, i_m and ε sufficiently small such that $P_1 = \cdots = P_{\ell} = P_{i_1} - \varepsilon = \cdots P_{i_m} - \varepsilon = 0$, has a connected component D contained in C.

- maybe too many non empty intersections
- trick to reach general position: again infinitesimals
- complexity single exponential $s^{k+1}d^{O(k)}$.

3.3 Compute connectivity

- perform (ETR) parametrically and then make a recursion: roadmap construction
- roadmap: dimension at most one, connected in each connected component, meets each connected component of each fiber along the X_1 -axis
- construct connecting paths
- counts connected components: b_0 Betti number (dimension of homology)
- complexity $s^{k+1}d^{O(k^2)}$

3.4 Use parametrized paths

- parametrized connecting paths
- cover by contractible sets (parametrized paths)
- describe connected components: unions of points parametrically connected to points in the same connected components
- cover by closed contractible sets (construction of Gabrielov Vorobjov)
- use spectral sequences (slightly more advanced algebraic topology)
- computation of b_1 using Mayer-Vietoris sequences (Basu/Pollack/R 2004)
- computation of the first Betti numbers (Basu 2004): more spectral sequences

 A_1, \ldots, A_n sub-complexes of a finite simplicial complex A such that $A = A_1 \cup \cdots \cup A_n, A_{i_0,\ldots,i_p}$ the sub-complex $A_{i_0} \cap \cdots \cap A_{i_p}$.

 $C^{i}(A)$ the Q-vector space of i co-chains of A, and $C^{\bullet}(A)$, the complex

$$\cdots \to C^{q-1}(A) \xrightarrow{d} C^{q}(A) \xrightarrow{d} C^{q+1}(A) \to \cdots$$

where $d: C^q(A) \to C^{q+1}(A)$ are the usual co-boundary homomorphisms.

The generalized Mayer-Vietoris sequence is the following exact sequence

$$0 \longrightarrow C^{\bullet}(A) \xrightarrow{r} \prod_{i_0} C^{\bullet}(A_{i_0}) \xrightarrow{\delta_1} \prod_{i_0 < i_1} C^{\bullet}(A_{i_0, i_1})$$

$$\cdots \xrightarrow{\delta_{p-1}} \prod_{i_0 < \dots < i_p} C^{\bullet}(A_{i_0,\dots,i_p}) \xrightarrow{\delta_p} \prod_{i_0 < \dots < i_{p+1}} C^{\bullet}(A_{i_0,\dots,i_{p+1}}) \cdots$$

where r is induced by restriction and the connecting homomorphisms δ are defined by

$$(\delta\omega)_{i_0,\dots,i_{p+1}}(s) = \sum_{0 \le i \le p+1} (-1)^i \omega_{i_0,\dots,\hat{i_i},\dots,i_{p+1}}(s),$$

(^denotes omission). Exactness is classical.

Consider the following complex (which is no more exact)

$$0 \longrightarrow \prod_{i_0} C^{\bullet}(A_{i_0}) \xrightarrow{\delta_1} \prod_{i_0 < i_1} C^{\bullet}(A_{i_0, i_1}) \xrightarrow{\delta_2} \prod_{i_0 < \dots < i_p} C^{\bullet}(A_{i_0, \dots, i_2}) \cdots$$

$$\cdots \xrightarrow{\delta_{p-1}} \prod_{i_0 < \dots < i_p} C^{\bullet}(A_{i_0,\dots,i_p}) \xrightarrow{\delta_p} \prod_{i_0 < \dots < i_{p+1}} C^{\bullet}(A_{i_0,\dots,i_{p+1}}) \cdots$$

and the induced cohomology complex.

Proposition 3.3 Let A_1, \ldots, A_n be sub-complexes of a finite simplicial complex A such that $A = A_1 \cup \cdots \cup A_n$ and each A_i is contractible. Then, $b_1(A) = \dim((\delta_2)) - \dim((\delta_1))$, with

$$\prod_{i} H^{0}(A_{i}) \xrightarrow{\delta_{1}} \prod_{i < j} H^{0}(A_{i,j}) \xrightarrow{\delta_{2}} \prod_{i < j < \ell} H^{0}(A_{i,j,\ell})$$

in other words three by three intersections suffice to compute b_1 when the cover is closed and contractible.

Proof: consider the following bi-graded double complex $\mathcal{M}^{p,q}$, with a total differential $D = \delta + (-1)^p d$, where

$$\mathcal{M}^{p,q} = \prod_{i_0,\dots,i_p} C^q(A_{i_0,\dots,i_p}).$$

consider two spectral sequences (corresponding to taking horizontal or vertical filtrations respectively)

one of them degenerates

3.5 Practical computations of b_1

- Basu and Kettner (submitted to SOCG)
- use spectral sequences and consider intersections three by three
- now apply CAD (rather than critical point method)
- able to compute the topology of the union of 10 ellipsoids in three space
- classical CAD fails

3.6 Quadratic case: polynomial in k

- quadratic case, ℓ quadratic equations, dimension k
- derivatives of quadratic are linear
- go to $\ell + k$ variables
- a generic linear combination of ℓ matrices is of rank $k \ell + 1$
- go to $2\ell 1$ variables using linear algebra
- use there single exponential complexity

quadratic case (continued)

- few top Betti numbers (Saugata Basu)
- use Agrachev geometric results
- Open problems
- All Betti numbers (single exponential complexity)?
- Stratification (single exponential complexity)?
- Complexity in the quadratic case: besides ETR, global optimization and top Betti numbers, what is polynomial-time complexity? Counting connected components?